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Digital holographic microscopy with high numerical aperture: wide z range reconstruction

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Abstract: A holographic microscopy algorithm is proposed enabling to deal with high numerical aperture holograms. Hologram reconstruction kernel performs under afocal conditions, which allows keeping the full NA over wide defocus range.

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1. Introduction

Digital holography aims at recording, on a CCD or CMOS sensor, the interference pattern between an object field wavefront (amplitude and phase of the wave scattered by the investigated object) and a reference wavefront. Three dimensional information about the investigated scene is further retrieved considering light back-propagation techniques [1]. Methods have been proposed for the specific case of digital holographic microscopy [2, 3], but these allow optimal amplitude and phase reconstruction only in the plane where the correction is calculated. These are therefore limited to 2D samples. Recently, we proposed a reconstruction method allowing a distortion-less reconstruction in both object and image half spaces [4]. In the following, we discuss of its extension to high numerical aperture (NA up to 1.4) [5].

2. Principles of the holographic reconstruction with high numerical aperture objectives

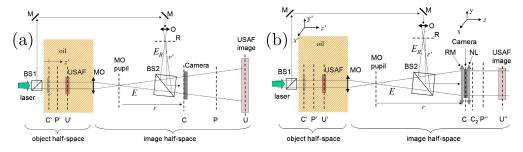


Fig. 1. (Color online) Typical holographic microscopy set-up for (a) recording, (b) reconstructing. BS1 and BS2, beam splitters. C, P, and U respectively denote the camera, the pupil (optimal plane of the MO), and the USAF image planes. The "X'" planes are the images of the aforemensioned planes through the MO.

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The arrangement for high NA holographic reconstruction is proposed Fig. 1. It consists of a classical off-axis holography arrangement with an immersion Microscope Objective (MO). In classical microscopic imaging, both the object and the sensor have to be positioned in the optimal planes of the objective, *i.e.* planes P and P' (see Fig. 1 for details). As a matter of fact, these planes are, by design, the ones for which the optical aberrations are minimal. Thus, optimal imaging is achieved when camera planes (C and C'), object planes (U and U'), and optimal planes (P and P') coincides (U = P = C and U' = P' = C'). Holographic imaging is less restrictive and only needs the object to be in the optimal plane to optimally operate (U = P and U' = P'). Indeed, the field in the camera plane ($C \neq U$) can be digitally propagated from camera P to optimal plane P by using standard reconstruction method with quadratic kernel. We propose here to go further and to conserve optimal resolution for an object not located in the optimal plane i.e. P is P [5].

The proposed method, which apply for high NA hologram reconstruction, is composed of two main steps:

- 1. Field reconstruction (with a quadratic kernel) in the optimal plane P' that allows retrieving the corrected amplitude and phase in plane.
- 2. Field propagation from P' to U'. The complete propagation kernel has to be used to account for the immersion medium and the large illumination angles.

We also need to have a precise knowledge of the location of the optimal plane P', the phase correction to be applied in plane P', and the imaging magnification G of the optical system, which can be obtained by imaging a calibrated object such as an USAF target, to operate under optimal conditions.

3. Optimal holographic reconstruction

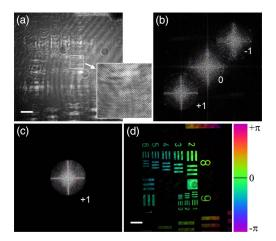


Fig. 2. (Color online) Principles of reconstruction. (a) Hologram H_C (carrier fringes shown in inset). (b) Hologram \tilde{H}_2 for $dk_x = dk_y = 0$ (in arbitrary log scale). (c) Hologram \tilde{H}_3 (details about the filtering are in the main text. (d) Hologram H_3 reconstructed phase is associated with the RGB LUT.

The hologram recorded in the camera plane C is given by

$$H_C = |E + E_R|^2 = |E|^2 + |E_R|^2 + EE_R^* + E^*E_R,$$
(1)

where E and E_R are both the signal and reference field in the camera plane C. Here, two cases have to be distinguished: the object is in optimal plane P' or the object is outside P'. The hologram $H_{P'}$ in plane P' can be calculated considering the method proposed in [4]. We here recall the main aspects of this procedure, which are illustrated by Fig. 2.

3.1. Reconstruction for U' = P'

The first step of the reconstruction consists in multiplying the hologram H_C (see Fig. 2(a)) by a complex matrix C_{RM} which compensate for wave front curvature and off-axis tilt of the reference. The curvature and tilt compensated

hologram H_1 can therefore be calculated considering

$$H_1(x,y) = H_C(x,y) C_{\text{RM}} = H_C(x,y) e^{jk(x^2 + y^2)/2r'} e^{j(dk_x x + dk_y y)}.$$
 (2)

The MO-induced wave front curvature is considered as a second step. This is done by multiplying hologram H_1 by a numerical lens (NL) $C_{\rm NL}$ located in the camera plane C. The hologram H_2 is such that

$$H_2(x,y) = H_1(x,y) C_{NL}(x,y) = H_1(x,y) e^{-jk(x^2+y^2)/2r},$$
 (3)

where r is the focal of the NL that is adjusted such as the MO+NL optical system is afocal. FFT of H_2 , denoted \tilde{H}_2 is proposed Fig. 2(b) for $dk_x = dk_y = 0$. From \tilde{H}_2 the selection of the +1 grating order is performed by applying a circle crop of radius k_{max} and adjusting $dk_{x,y}$ to bring the +1 order in the center of the k space. This consists of the hologram \tilde{H}_3 illustrated Fig. 2(c) and obtained with $dk_x = 255$, $dk_y = -244.52$, and $k_{max} = 162$ pixels. Finally, as shown in Ref. [5], knowing the optical magnification G makes it possible to reconstruct the hologram $H_{P'}$ from \tilde{H}_3 by

$$H_{P'}\left(x/G, y/G, z'_{P'}\right) = \text{FFT}^{-1}\left[e^{j\left(G^{2}k_{x}^{2} + G^{2}k_{y}^{2}\right)z'_{P'}/2k_{m}}\tilde{H}_{3}\left(Gk_{x}, Gk_{y}\right)\right],\tag{4}$$

where $k_m = n_m k$ is the wave vector in oil. This result is proposed Fig. 2(d).

3.2. Reconstruction for $U' \neq P'$

The hologram H'_U in the plane U' can be obtained from hologram H'_P (see the derivations in the previous section and in Refs. [4,5]). However, the propagation between U' and P' occurs in the oil, and numerical apertures can be large. It is therefore mandatory to deal with this propagation using the exact propagation kernel $e^{-jk_z'z'}$. Here k_z' is defined as $k_z' = \sqrt{k_m^2 - k_x'^2 - k_y'^2}$, where $k_m = n_m 2\pi/\lambda$, and $k_{x,y}' = Gk_{x,y}$. The hologram in the plane is is finally given by

$$H_{U'}(x', y', z') = \text{FFT}^{-1} \left[e^{jk'_z(z'-z'_p)} \text{FFT} \left[H_{P'}(x', y', z'_{P'}) \right] \right]. \tag{5}$$

Illustration of the method benefits is provided by Fig. 3. Here from the optimal hologram Fig. 3(d), on can realize

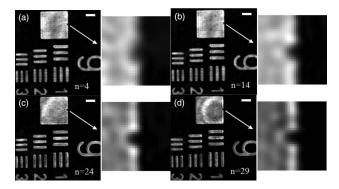


Fig. 3. Reconstruction of high NA holograms for various defocus. (a) $z'-z'_p=-47.69~\mu m$. (b) $z'-z'_p=-23.39~\mu m$. (c) $z'-z'_p=0.8~\mu m$. (d) $z'-z'_p=12.84~\mu m$. Scale bar is 3 μm .

that our method allow to keep a good resolution with defocus up to $-50\mu m$. The same result is obtained for positive defocus but is not represented here. Therefore we are possible to keep an high resolution reconstruction over a large defocus range.

4. Conclusion

We proposed a two step reconstruction method operating with high numerical aperture holograms (up to NA = 1.4). The benefits of the methods have been demonstrated through the reconstruction of holograms recorded with a $\times 60$ NA = 1.4 oil immersion MO, proving the ability to keep almost full resolution in a $[-50 \ \mu \text{m}; 50 \ \mu \text{m}]$ defocus range.

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