

A mixed boundary q KZ equation: integrability, graphical solutions, and connections

Caley Finn, LAPTh

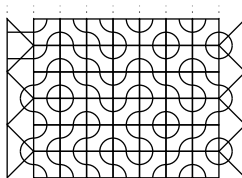
November 2015, Montpellier

Outline

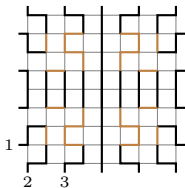
- ① Temperley–Lieb loop model
- ② Solutions of the q KZ equation
- ③ Hecke algebra and special functions

Outline

Temperley–Lieb loop model



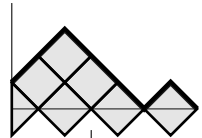
Fully packed loops



Razumov–Stroganov conjectures

Stochastic process
 $M|\Psi_0\rangle = 0$

Ballot paths



q KZ solutions
Hecke algebras

Section 1

Temperley–Lieb loop model

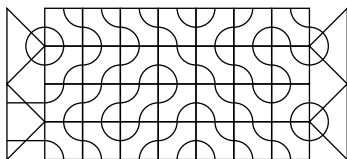
Temperley–Lieb $O(n)$ loop model

Random tiling with

- Tiles: left boundary, bulk, right boundary



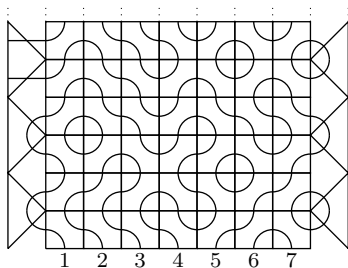
- Mixed boundaries: open or reflecting at left, always reflecting at right
- An example configuration with four rows:



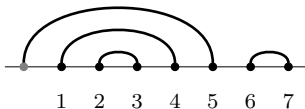
- Closed loops are given weight $n = -(t + t^{-1})$
- Choosing $t = e^{\pm 2\pi i/3}$ gives loops weight $n = 1$

Link patterns

- Consider now a semi-infinite lattice, width N



- Represent connectivity along the bottom edge by left-extended link patterns

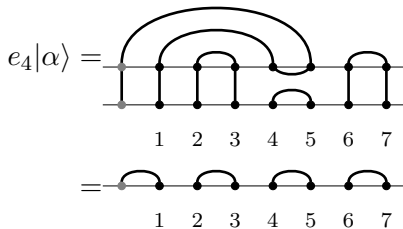
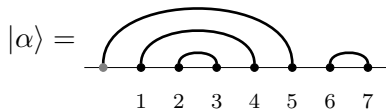


Action on link patterns

- Introduce operators e_0, e_1, \dots, e_{N-1}

$$e_0 = \begin{array}{c} \frown \\ | \quad \cdots \quad | \\ 1 \quad 2 \quad \quad N \end{array} \quad e_i = \begin{array}{c} | \quad \cdots \quad | \quad \frown \\ | \quad \cdots \quad | \quad \smile \\ 1 \quad \quad i-1 \quad i \quad i+1 \quad i+2 \quad \quad N \end{array}$$

- Act on a link pattern



Temperley–Lieb algebra

Introduce the one boundary Temperley–Lieb algebra

- The operators e_0, e_1, \dots, e_{N-1} are the generators

$$e_0 = \begin{array}{c} \frown \\ | \quad \cdots \quad | \\ 1 \quad 2 \quad \quad N \end{array} \quad e_i = \begin{array}{c} | \quad \cdots \quad | \quad \smile \\ 1 \quad \quad i-1 \quad i \quad i+1 \quad i+2 \quad \quad N \end{array}$$

- Relations

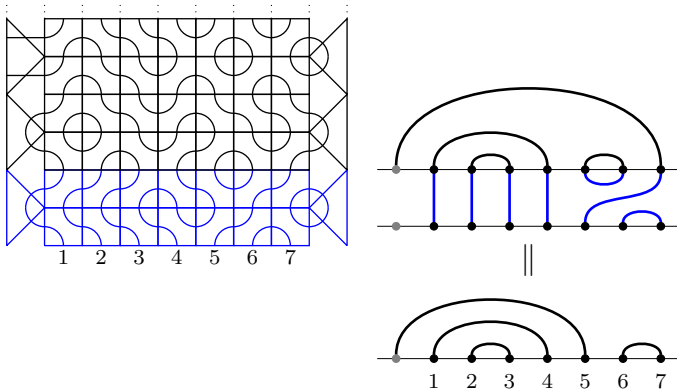
$$e_i^2 = -(t + t^{-1})e_i, \quad e_i e_{i\pm 1} e_i = e_i, \quad e_i e_j = e_j e_i, \quad |i - j| > 1, \\ e_0^2 = e_0, \quad e_1 e_0 e_1 = e_1$$

- Example

$$e_i^2 = \dots \left| \begin{array}{c} \smile \\ \smile \end{array} \right| \dots = -(t + t^{-1}) \dots \left| \begin{array}{c} \smile \\ \smile \end{array} \right| \dots \\ = -(t + t^{-1})e_i$$

Adding rows

- Adding a pair of rows transforms the link pattern



- In terms of the Temperley–Lieb generators

The diagram shows the link pattern from the previous diagram (the one with arcs connecting (1,6), (2,3), (3,4), and (6,7)) followed by an equals sign and the product of two Temperley-Lieb generators, $e_5 e_6$. The generator e_5 is represented by a vertical line connecting dots 4 and 5, and the generator e_6 is represented by a crossing between dots 6 and 7.

Transfer matrix

- The *double row transfer matrix* gives the probability of transitions between link patterns
- Give weights to tiles, e.g.

$$\square \sim a(w) \quad \square \sim b(w)$$

- For $N = 2$

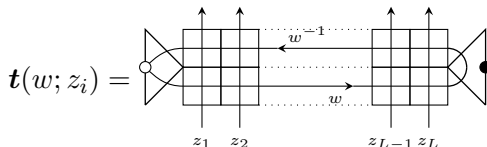
$$t(w) = \begin{matrix} |\Omega\rangle & |\alpha\rangle \\ |\Omega\rangle & * \\ |\alpha\rangle & \end{matrix} \quad |\Omega\rangle = \text{---} \overbrace{\quad} \quad \text{---} \quad |\alpha\rangle = \text{---} \cdot \overbrace{\quad} \quad \text{---}$$

Contributions from



Transfer matrix

- The general case defined pictorially



- Assigns weights to tiles

$$w \begin{array}{|c|} \hline \square \\ \hline \end{array} \begin{array}{|c|} \hline \rightarrow \\ \hline \end{array} z = a(w, z) \begin{array}{|c|} \hline \square \\ \hline \end{array} + b(w, z) \begin{array}{|c|} \hline \square \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline \begin{array}{|c|} \hline \square \\ \hline \end{array} \\ \hline \end{array} \begin{array}{|c|} \hline \rightarrow \\ \hline \end{array} w = a_0(w) \begin{array}{|c|} \hline \begin{array}{|c|} \hline \square \\ \hline \end{array} \\ \hline \end{array} + b_0(w) \begin{array}{|c|} \hline \begin{array}{|c|} \hline \square \\ \hline \end{array} \\ \hline \end{array}$$

- Expanding gives a weighted sum over all double row configurations

Integrability

- Choose the weights so that the model is *integrable*

$$[\mathbf{t}(w; z_i), \mathbf{t}(v; z_i)] = 0$$

- Then the eigenvectors are independent of the spectral parameter

$$\mathbf{t}(w; z_i)|\Psi(z_i)\rangle = \Lambda(w)|\Psi(z_i)\rangle$$

- Integrability in this model arises from solutions of the Yang–Baxter and reflection relations

Yang–Baxter and reflection relations

- Yang–Baxter relation

$$R_i(w)R_{i+1}(wz)R_i(z) = R_{i+1}(z)R_i(wz)R_{i+1}(w)$$

- Reflection relation

$$K_0(z)R_1(wz)K_0(w)R_1(w/z) = R_1(w/z)K_0(w)R_1(wz)K_0(z)$$

- Satisfied by the bulk R matrix, and boundary K matrix

$$R_i(z) = \frac{t - t^{-1}z}{tz - t^{-1}} \mathbb{1} - \frac{z - 1}{tz - t^{-1}} e_i$$
$$K_0(z) = \frac{(1 - z^{-1}\zeta_1^{-1})(z - t\zeta_1)}{(z - \zeta_1)(t - z^{-1}\zeta_1^{-1})} \mathbb{1} - \frac{(1 - t)(z - z^{-1})}{(z - \zeta_1)(t - z^{-1}\zeta_1^{-1})} e_0$$

- The transfer matrix weights are related to the coefficients in these expressions

Interlacing condition

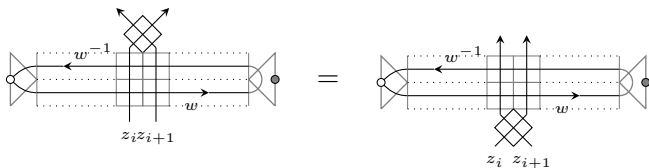
- The R operator is represented graphically as

$$R_i(z_i/z_{i+1}) = \begin{array}{c} \begin{array}{ccc} & \nearrow & \\ & \searrow & \\ & \nearrow & \\ & \searrow & \end{array} \\ z_i \quad z_{i+1} \end{array}$$

- We will need the bulk interlacing condition

$$R_i\left(\frac{z_i}{z_{i+1}}\right) \mathbf{t}(w; \dots, z_i, z_{i+1}, \dots) = \mathbf{t}(w; \dots, z_{i+1}, z_i, \dots) R_i\left(\frac{z_i}{z_{i+1}}\right)$$

- Or pictorially



The transition matrix

- Taking $-(t + t^{-1}) = 1$ we can obtain a stochastic transition matrix

$$M = \alpha \frac{\partial}{\partial w} \log \mathbf{t}(w; z_i = 1) \Big|_{w=1} + \text{const.}$$

where

$$M = a(e_0 - \mathbb{1}) + \sum_{i=1}^{L-1} (e_i - \mathbb{1}), \quad [M, t(u)] = 0$$

- M has left eigenvector $(1, \dots, 1)$ with eigenvalue 0. Perron–Frobenius tells us the corresponding right eigenvector is the unique stationary state.
- Will assume there is a transfer matrix eigenvector such that

$$\mathbf{t}(w; z_i) |\Psi_0(z_i)\rangle = |\Psi_0(z_i)\rangle$$

then

$$M |\Psi_0(z_i = 1)\rangle = 0$$

so $|\Psi_0(z_i)\rangle$ is unique (in the neighbourhood of $z_i = 1$)

The q KZ equations

- Using the definition of the stationary state, and the interlacing condition

$$\begin{aligned} R_i(z_i/z_{i+1})|\Psi_0(z_i)\rangle &= R_i(z_i/z_{i+1})t(w; z_i, z_{i+1})|\Psi_0(z_i)\rangle \\ &= t(w; z_{i+1}, z_i)R_i(z_i/z_{i+1})|\Psi_0(z_i)\rangle \end{aligned}$$

- Then from uniqueness can show that

$$R_i(z_i/z_{i+1})|\Psi_0(\dots, z_i, z_{i+1}, \dots)\rangle = |\Psi_0(\dots, z_{i+1}, z_i, \dots)\rangle$$

This is the bulk part of the q KZ equation.

- The boundary equations

$$\begin{aligned} K_0(z_1^{-1})|\Psi(z_1, z_2, \dots, z_N)\rangle &= |\Psi(z_1^{-1}, z_2, \dots, z_N)\rangle, \\ |\Psi(z_1, \dots, z_{N-1}, z_N)\rangle &= |\Psi(z_1, \dots, z_{N-1}, t^3 z_N^{-1})\rangle \end{aligned}$$

Summary so far

- We have a stochastic process

$$M = a(e_0 - \mathbb{1}) + \sum_{i=1}^{L-1} (e_i - \mathbb{1})$$

with stationary distribution $|\Psi_0\rangle$ such that $M|\Psi_0\rangle = 0$

- To find $|\Psi_0\rangle$ we will find the more general vector

$$|\Psi_0\rangle \rightarrow |\Psi_0(z_1, \dots, z_N)\rangle$$

by solving the q KZ equations

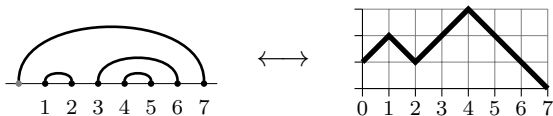
- Setting $z_i = 1$ will give us back the stationary distribution. But we are also interested in the general solution!

Section 2

Solutions of the q KZ equation

Bijection to Ballot paths

- Left-extended link patterns are in bijection with Ballot paths



- Working from right to left:
 - Arch opening - step left and up
 - Arch closing - step left and down
- Gives a Ballot path: sequence of non-negative heights

$$\alpha = (\alpha_0, \dots, \alpha_N)$$

with $\alpha_N = 0$, and $\alpha_{i+1} - \alpha_i = \pm 1$.

The Temperley–Lieb algebra

- Generators mapped to tiles

$$e_i = \left| \cdots \right|_{1 \quad i-1} \left| \begin{array}{c} \cup \\ \cap \end{array} \right|_{i \quad i+1} \left| \cdots \right|_{i+2 \quad N} \rightarrow e_i = \begin{array}{c} \diamond \\ \vdots \\ i \end{array}$$

- Bulk relations $e_i^2 = -(t + t^{-1})e_i$, $e_i e_{i\pm 1} e_i = e_i$:

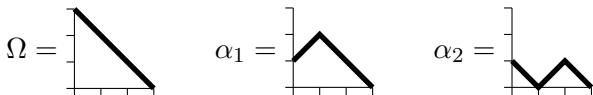
$$\begin{array}{c} \diamond \\ \diamond \\ \vdots \\ i \end{array} = -(t + t^{-1}) \begin{array}{c} \diamond \\ \vdots \\ i \end{array} \quad \begin{array}{c} \diamond \\ \diamond \\ \diamond \\ \vdots \\ i \quad i+1 \end{array} = \begin{array}{c} \diamond \\ \diamond \\ \diamond \\ \vdots \\ i-1 \quad i \end{array} = \begin{array}{c} \diamond \\ \vdots \\ i \end{array}$$

- Boundary relations $e_0^2 = e_0$, $e_1 e_0 e_1 = e_1$:

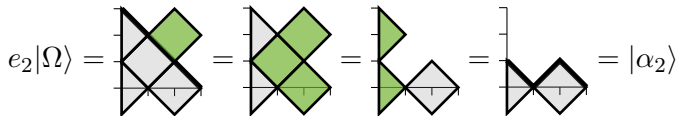
$$\begin{array}{c} \triangleleft \\ \triangleleft \\ \vdots \\ 0 \end{array} = \begin{array}{c} \triangleleft \\ \vdots \\ 0 \end{array} \quad \begin{array}{c} \diamond \\ \diamond \\ \diamond \\ \vdots \\ 0 \quad 1 \end{array} = \begin{array}{c} \diamond \\ \vdots \\ 1 \end{array}$$

Action on Ballot paths

- Ballot paths of length $N = 3$



- Example



- Matrix form

$$e_2 = \begin{matrix} & |\Omega\rangle & |\alpha_1\rangle & |\alpha_2\rangle \\ \begin{matrix} |\Omega\rangle \\ |\alpha_1\rangle \\ |\alpha_2\rangle \end{matrix} & \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 1 & -(t+t^{-1}) \end{pmatrix} \end{matrix}$$

Components of the q KZ equation

- Write the stationary state vector in the Ballot path basis as

$$|\Psi(z_1, \dots, z_N)\rangle = \sum_{\alpha} \psi_{\alpha}(z_1, \dots, z_N) |\alpha\rangle$$

- The bulk part of the q KZ equation

$$R_i(z_i/z_{i+1}) |\Psi(z_1, \dots, z_N)\rangle = |\Psi(\dots, z_{i+1}, z_i, \dots)\rangle$$

- Component form

$$\sum_{\alpha} \psi_{\alpha}(z_1, \dots, z_N) (e_i |\alpha\rangle) = \sum_{\alpha} (T_i(-1) \psi_{\alpha}(z_1, \dots, z_N)) e_i |\alpha\rangle$$

where the $T_i(u)$ are Hecke operator acting on Laurent polynomials

- The boundary equations

$$\begin{aligned} K_0(z_1^{-1}) |\Psi(z_1, z_2, \dots, z_N)\rangle &= |\Psi(z_1^{-1}, z_2, \dots, z_N)\rangle, \\ |\Psi(z_1, \dots, z_{N-1}, z_N)\rangle &= |\Psi(z_1, \dots, z_{N-1}, t^3 z_N^{-1})\rangle \end{aligned}$$

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Solution of the q KZ equation

Theorem (de Gier, Pyatov 2010)

The solutions of the q KZ equation have a factorised form

$$\psi_\alpha(z_1, \dots, z_N) = \prod_{i,j}^{\nearrow u_{i,j}} T_i(u_{i,j}) \psi_\Omega(z_1, \dots, z_N)$$

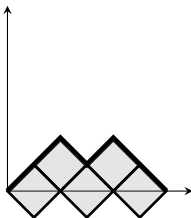
The product is constructed using a graphical representation of the Hecke generators

$$T_0(u) = \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \triangleleft u \triangleright \\ \text{---} \\ \text{---} \\ \text{---} \\ 0 \quad 1 \end{array}, \quad T_i(u) = \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \diamond u \diamond \\ \text{---} \\ \text{---} \\ \text{---} \\ i-1 \quad i \quad i+1 \end{array}.$$

These are operators on Laurent polynomials, which also satisfy Yang–Baxter and reflection relations.

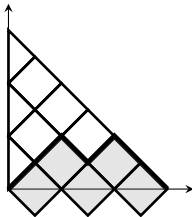
Factorised solutions

- Factorised solution for $\psi_\alpha(z_1, \dots, z_N)$



Factorised solutions

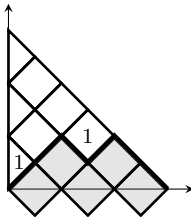
- Factorised solution for $\psi_\alpha(z_1, \dots, z_N)$
- Fill to maximal Ballot path $\Omega = (N, N - 1, \dots, 0)$



Factorised solutions

- Factorised solution for $\psi_\alpha(z_1, \dots, z_N)$
- Fill to maximal Ballot path $\Omega = (N, N - 1, \dots, 0)$
- Label corners with 1
- Label remaining tiles by rule

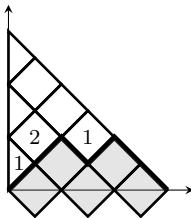
$$u_{i,j} = \max\{u_{i+1,j-1}, u_{i-1,j-1}\} + 1$$



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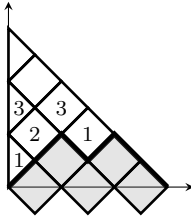
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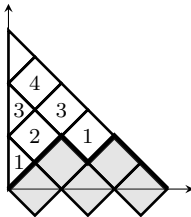
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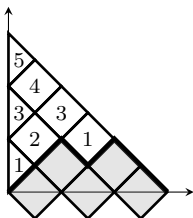
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Factorised solutions

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$$u_{i,j} = \max\{u_{i+1,j-1}, u_{i-1,j-1}\} + 1$$



$$\psi_\alpha = T_0(1).T_1(2)T_0(3).T_3(1)T_2(3)T_1(4)T_0(5)\psi_\Omega$$

and

$$\psi_\Omega = \Delta_t^-(z_1, \dots, z_N)\Delta_t^+(z_1, \dots, z_N)$$

Stationary state solutions

- The stationary state can be calculated directly from the factorised solutions

$$|\Psi_0^{(2)}\rangle = \frac{1}{Z_2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{array}{c} \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \text{---} \end{array}$$

$$|\Psi_0^{(3)}\rangle = \frac{1}{Z_3} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \begin{array}{c} \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \text{---} \end{array}$$

$$|\Psi_0^{(4)}\rangle = \frac{1}{Z_4} \begin{pmatrix} 1 \\ 3 \\ 8 \\ 9 \\ 3 \\ 9 \end{pmatrix} \begin{array}{c} \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \\ \text{---} \overbrace{\text{---}}^{\text{---}} \text{---} \end{array}$$

for $\zeta_0 = t$, $t = e^{\pm 2\pi i/3}$.

- Will return to the integer entries later
- Computing the entries for large N is difficult (no closed form)

Alternate filling

Fill with consecutive integers along rows, e.g. for previous shape tilted by 45°

$$\begin{aligned} & \psi_{4,2,1}(u_1 + 1, u_2 + 1, u_3 + 1) \\ = & \begin{array}{|c|c|c|c|} \hline & u_1+1 & & & \\ \hline & 4 & u_1+3 & u_1+2 & u_1+1 & \\ \hline & & u_2+1 & & & \\ \hline & & 2 & u_2+1 & & \\ \hline & & & u_3+1 & & \\ \hline & & & 1 & & \\ \hline \end{array} \\ & = \mathcal{T}_1(u_3 + 1)\mathcal{T}_2(u_2 + 1)\mathcal{T}_3(u_1 + 1)\psi_\Omega \end{aligned}$$

where

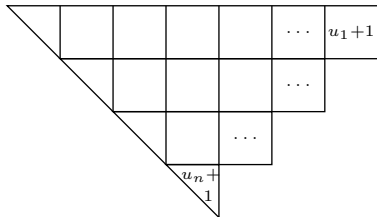
$$\mathcal{T}_a(u + 1) = T_{a-1}(u + 1) \dots T_1(u + a - 1)T_0(u + a)$$

gives a row of length a , numbered from $u + 1$.

Staircase diagram

- Call the largest such element the *staircase diagram*:

$$\psi_{\bar{a}_1, \dots, \bar{a}_n}(u_1 + 1, \dots, u_n + 1) =$$



where $n = \lfloor N/2 \rfloor$, $\bar{a}_i = N - 2i + 1$

- In terms of Hecke generators

$$\begin{aligned} & \psi_{\bar{a}_1, \dots, \bar{a}_n}(u_1 + 1, \dots, u_n + 1) \\ &= \mathcal{T}_{N-2n+1}(u_n + 1) \dots \mathcal{T}_{N-3}(u_2 + 1) \mathcal{T}_{N-1}(u_1 + 1) \psi_{\Omega} \end{aligned}$$

Generalised sum rule

Theorem (de Gier, F)

The staircase diagram has the expansion

$$\psi_{\bar{a}_1, \dots, \bar{a}_n}(u_1 + 1, \dots, u_n + 1) = \sum_{\alpha} c_{\alpha} \psi_{\alpha}(z_1, \dots, z_N),$$

where the coefficients c_{α} are non-zero and are monomials in

$$y_i = -\frac{[u_i]}{[u_i + 1]}, \quad \tilde{y}_i = -B_0(u_i + 1).$$

- Using the notation

$$[u] = [u]_t = \frac{t^u - t^{-u}}{t - t^{-1}}$$

- Proof of the sum rule requires expanding staircase diagram in two stages.

First expansion

The first stage of the expansion gives the form of the coefficients.

Lemma (First expansion)

$$\begin{aligned} & \mathcal{T}_{a_n}(u_n + 1) \dots \mathcal{T}_{a_1}(u_1 + 1) \psi_\Omega \\ &= \prod_{i=n, n-1, \dots, 1} (\mathcal{T}_{a_i}(1) + y_i \mathcal{T}_{a_{i-1}}(1) + \tilde{y}_i) \psi_\Omega \end{aligned}$$

where

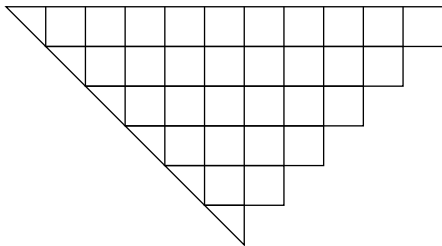
$$y_i = -\frac{[u_i]}{[u_i + 1]}, \quad \tilde{y}_i = -B_0(u_i + 1)$$

First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

- Start from the empty outline.
- Working from top down, a row may be left empty (factor \tilde{y}_i), filled one short (factor y_i), or filled completely (no additional factor).
- Delete empty rows and boxes.

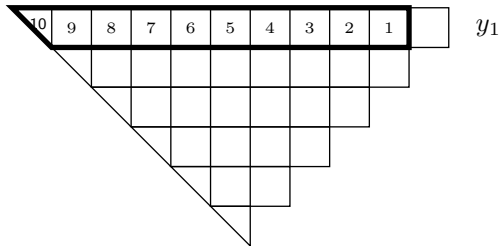


First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

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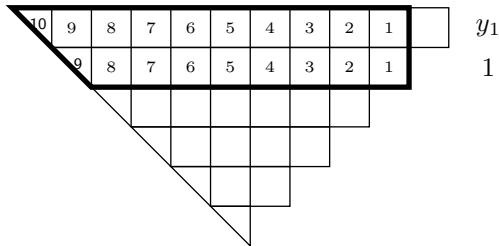


First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

- Start from the empty outline.
- Working from top down, a row may be left empty (factor \tilde{y}_i), filled one short (factor y_i), or filled completely (no additional factor).
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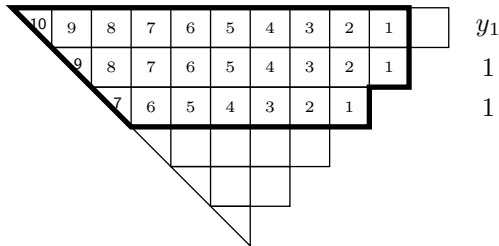


First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

- Start from the empty outline.
- Working from top down, a row may be left empty (factor \tilde{y}_i), filled one short (factor y_i), or filled completely (no additional factor).
- Delete empty rows and boxes.

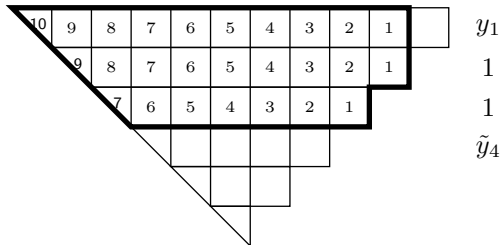


First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

- Start from the empty outline.
- Working from top down, a row may be left empty (factor \tilde{y}_i), filled one short (factor y_i), or filled completely (no additional factor).
- Delete empty rows and boxes.

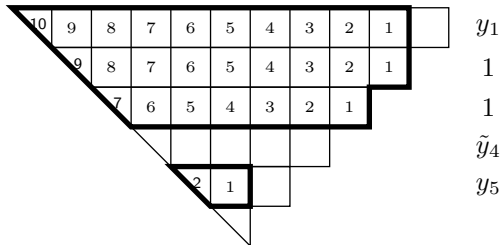


First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

- Start from the empty outline.
- Working from top down, a row may be left empty (factor \tilde{y}_i), filled one short (factor y_i), or filled completely (no additional factor).
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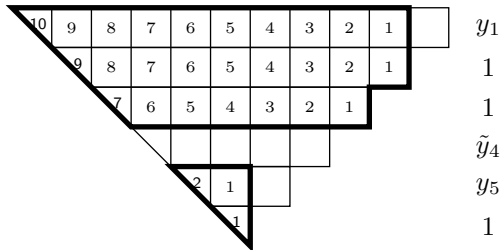


First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

- Start from the empty outline.
- Working from top down, a row may be left empty (factor \tilde{y}_i), filled one short (factor y_i), or filled completely (no additional factor).
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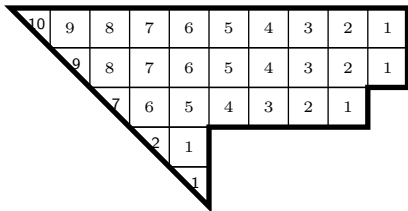


First expansion terms

Procedure to expand

$$(\mathcal{T}_{\bar{a}_n}(1) + y_n \mathcal{T}_{\bar{a}_n-1}(1) + \tilde{y}_n) \dots (\mathcal{T}_{\bar{a}_1}(1) + y_1 \mathcal{T}_{\bar{a}_1-1}(1) + \tilde{y}_1) \psi_\Omega$$

- Start from the empty outline.
- Working from top down, a row may be left empty (factor \tilde{y}_i), filled one short (factor y_i), or filled completely (no additional factor).
- Delete empty rows and boxes.



- Coefficient $y_1 \tilde{y}_4 y_5$

Second expansion

When the resulting term is not a proper component ψ_α , a second expansion is required.

Lemma (Second expansion)

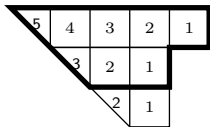
Let $\psi_\alpha(z_1, \dots, z_N)$ be a component of the qKZ solution, with last row of length $a + 1$, then

$$T_{a-1}(1) \dots T_1(a-1) T_0(a) \psi_\alpha(z_1, \dots, z_N) = \sum_{\alpha'} \psi_{\alpha'}(z_1, \dots, z_N)$$

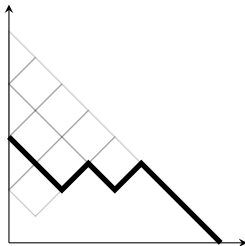
- The terms in the sum are found through a graphical rule, and all have coefficient 1.

Second expansion example

$$T_1(1)T_0(2)\psi_\alpha(z_1, \dots, z_N) =$$

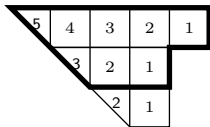


Ballot path

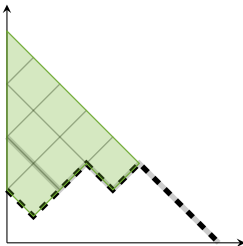


Second expansion example

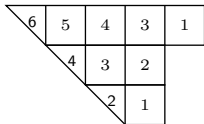
$$T_1(1)T_0(2)\psi_\alpha(z_1, \dots, z_N) =$$



Ballot path

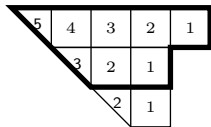


Terms

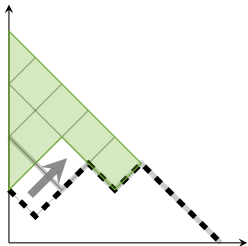


Second expansion example

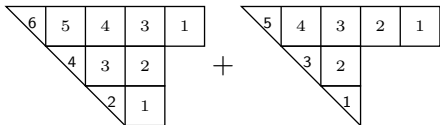
$$T_1(1)T_0(2)\psi_\alpha(z_1, \dots, z_N) =$$



Ballot path

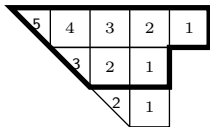


Terms

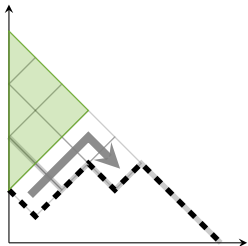


Second expansion example

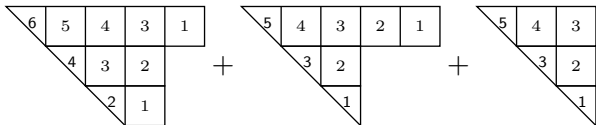
$$T_1(1)T_0(2)\psi_\alpha(z_1, \dots, z_N) =$$



Ballot path



Terms



Proof of the sum rule

- Recall the sum rule

$$\psi_{\tilde{a}_1, \dots, \tilde{a}_n}(u_1 + 1, \dots, u_n + 1) = \sum_{\alpha} c_{\alpha} \psi_{\alpha}(z_1, \dots, z_N),$$

where the coefficients c_{α} are non-zero and are monomials in y_i, \tilde{y}_i .

- We have shown via the two expansions that the staircase diagram can be expanded in terms of components ψ_{α} , with coefficients polynomials in y_i, \tilde{y}_i .
- To show that the coefficients are non-zero and monomials, we must show that each component ψ_{α} arises from a single term in the first expansion.

Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$

10	9	8	7	6	5	4	3	1
	8	7	6	5	4	3	2	
		6	5	4	3	2	1	
			3	2				
				1				

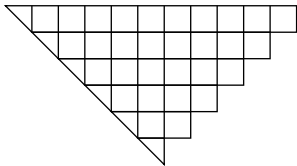
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$

10	9	8	7	6	5	4	3	1
	8	7	6	5	4	3	2	
		6	5	4	3	2	1	
			3	2				
				1				

- Draw empty maximal staircase



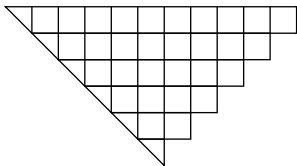
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$

10	9	8	7	6	5	4	3	1
	8	7	6	5	4	3	2	
		6	5	4	3	2	1	
			3	2				
				1				

- Draw empty maximal staircase
- Add rows to staircase, bottom up, in lowest place each fits



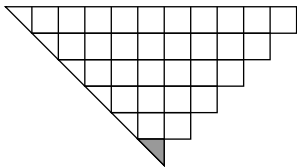
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$

10	9	8	7	6	5	4	3	1
	8	7	6	5	4	3	2	
		6	5	4	3	2	1	
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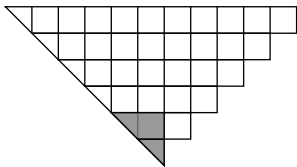
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$

10	9	8	7	6	5	4	3	1
	8	7	6	5	4	3	2	
		6	5	4	3	2	1	
				2				
					1			

- Draw empty maximal staircase
- Add rows to staircase, bottom up, in lowest place each fits



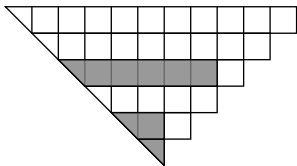
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$

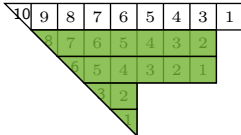
10	9	8	7	6	5	4	3	1
	8	7	6	5	4	3	2	
		6	5	4	3	2	1	
			4	2				
				1				

- Draw empty maximal staircase
- Add rows to staircase, bottom up, in lowest place each fits

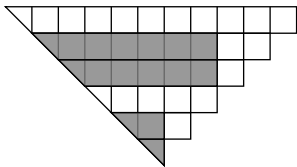


Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$


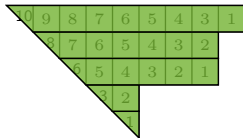
- Draw empty maximal staircase
- Add rows to staircase, bottom up, in lowest place each fits



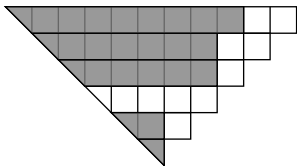
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$



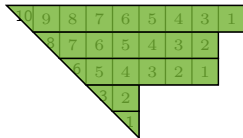
- Draw empty maximal staircase
- Add rows to staircase, bottom up, in lowest place each fits



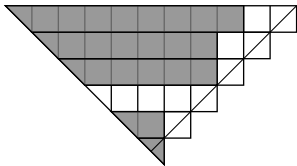
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$



- Draw empty maximal staircase
- Add rows to staircase, bottom up, in lowest place each fits
- Draw in ribbons, starting from outer diagonal



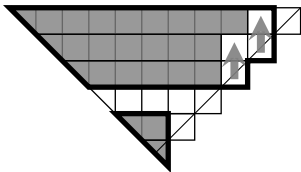
Example of the algorithm

- Work backwards from ψ_α to term from staircase expansion.

$$\psi_\alpha(z_1, \dots, z_N) =$$



- Draw empty maximal staircase
- Add rows to staircase, bottom up, in lowest place each fits
- Draw in ribbons, starting from outer diagonal



- Coefficient $c_\alpha = y_1 \tilde{y}_4 y_5$.

Specialisation of the sum rule

- At specialisation $u_i = 1$, $t = e^{\pm 2\pi i/3}$, all coefficients $c_\alpha = 1$.

$$\psi_{\bar{a}_1, \dots, \bar{a}_n}(2, \dots, 2) = \sum_{\alpha} \psi_{\alpha}(z_1, \dots, z_N),$$

giving the normalisation of the loop model stationary state vector

- At this point there is a closed form for the sum [Zinn-Justin 2007]. Setting $z_i = 1$ and $\zeta_1 = t = e^{\pm 2\pi i/3}$

$$\mathcal{Z}_N = \sum_{\alpha} \psi_{\alpha}(z_i = 1) = \prod_{k=1}^N \frac{\lfloor 3k/2 + 1 \rfloor (3k)! k!}{(2k+1)! (2k)!}$$

giving

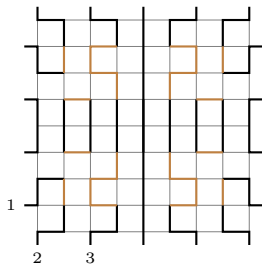
$$\mathcal{Z}_2 = 2, \quad \mathcal{Z}_3 = 6, \quad \mathcal{Z}_4 = 33 \dots$$

Razumov–Stroganov conjectures

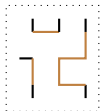
- The sequence \mathcal{Z}_N counts the number of vertically and horizontally symmetric fully packed loop diagrams (FPLs) of size $2N + 3$.

$$|\Psi_0^{(3)}\rangle = \frac{1}{\mathcal{Z}_3} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \begin{array}{c} \text{---} \text{---} \text{---} \\ \text{---} \text{---} \text{---} \\ \text{---} \text{---} \text{---} \end{array}$$

\leftrightarrow ?



Fully packed loops



- This connection between Temperley–Lieb loop models and FPLs is one of several Razumov–Stroganov type conjectures.

Section 3

Hecke algebra and special functions

Hecke algebra

The operators $T_i(u)$ are polynomial representations of a Baxterized Hecke algebra.

- Hecke algebra, \mathcal{H} , with relations

$$(T_i - t)(T_i + t^{-1}) = 0, \quad T_i T_{i+1} T_i = T_{i+1} T_i T_{i+1}, \quad i \geq 1$$
$$T_i T_j = T_j T_i, \quad \forall i, j : |i - j| > 1$$

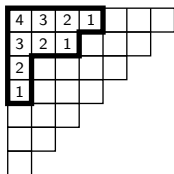
- Baxterized generator

$$T_i(u) = \begin{array}{c} \vdots \\ \vdots \\ \diamond \\ \vdots \\ \vdots \\ i-1 \quad i \quad i+1 \end{array} = T_i + t^{-1} - \frac{[u-1]}{[u]}$$

- We have also seen the boundary element T_0 but for the moment we will consider *periodic* systems (type A) without this generator.

q KZ solutions for type A

- Type A solutions given by partitions labelled with the same rule as the mixed boundary system [Kirilov, Lascoux 2000, de Gier, Pyatov 2010], e.g.



- The type A base function has form

$$\psi_{\Omega}^{(A)}(z_1, \dots, z_{2n}) = \Delta(z_1, \dots, z_n) \Delta(z_{n+1}, \dots, z_{2n+1})$$

- The set of solutions forms the Kazhdan–Lusztig basis

$$\mathcal{H}\Delta\Delta = \text{span}\{\psi_{\alpha}^{(A)}\}$$

with invariance property

$$\overline{\psi_{\alpha}^{(A)}} = \psi_{\alpha}^{(A)}$$

Sum rule for type A

- Sum rule given by consecutive integer labelling [de Gier, Lascoux, Sorrell 2012]

8	7	6	5	4	3	2
			...	3	2	
				.		
:						
		.				
3	2					
2						

- Set of all subpartitions gives the Young basis, e.g.

8	7	6	5	4	3	2
7	6	5	...	3	2	
6				.		
5						
:		.				
3	2					
2						

- Elements of the Young basis are specialised Macdonald polynomials.

Macdonald polynomials

- Within the Hecke algebra, can define a family of commuting elements

$$Y_i = T_i \dots T_{N-1} \omega T_1^{-1} \dots T_{i-1}^{-1}$$

with

$$[Y_i, Y_j] = 0$$

- These operators have a shared set of eigenfunctions E_λ , with

$$Y_i E_\lambda(z_1, \dots, z_N) = y(\lambda)_i E_\lambda(z_1, \dots, z_N)$$

and these E_λ are the non-symmetric Macdonald polynomials

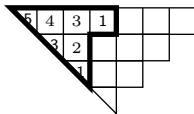
- The eigenfunctions are related by intertwiners

$$E_{s_i \lambda}(z_1, \dots, z_N) = T_i(u(\lambda)_i) E_\lambda(z_1, \dots, z_N)$$

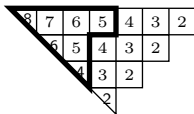
- For *periodic* boundaries, the intertwining relation gives exactly the Young basis elements

Hecke bases for mixed boundaries

- The elements of the q KZ solution correspond to a Kazhdan–Lusztig basis for the mixed boundary (type B) Hecke algebra [Shigechi 2014], e.g.



- The consecutive integer numbering gives an alternative basis, e.g.



- The expansion rules that led to the sum rule give the change of basis back to the KL basis
- Koornwinder instead of Macdonald polynomials

Conclusion and prospects

- The Temperley–Lieb loop model connects several areas of mathematics - integrability, combinatorics, representation theory, ...
- Though the stationary state is given through solutions of the q KZ equation we do not have a closed form
- The construction of the generalised sum rule gives a change of basis of the Hecke algebra, and relates Koornwinder polynomials to the q KZ solution
- We are hopeful that this will help us find closed forms for elements of the loop model stationary distribution